Logarithmic stability inequality in an inverse source problem for the heat equation on a waveguide

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Abstract

We prove logarithmic stability in the parabolic inverse problem of determining the space-varying factor in the source, by a single partial boundary measurement of the solution to the heat equation in an infinite closed waveguide, with homogeneous initial and Dirichlet data.

Mathematics subject classification 2010: 35R30, 35K05.

Keywords: Inverse problem, heat equation, time-dependent source term, stability inequality, Carleman estimate, partial boundary data.

1 Introduction

1.1 Statement and origin of the problem

Let $\omega \subset \mathbb{R}^{n-1}$, $n \geq 2$, be open and connected, with $\mathcal{C}^4$ boundary $\partial\omega$. Set $\Omega := \omega \times \mathbb{R}$ and $\Gamma := \partial\omega \times \mathbb{R}$. For $T \in (0, +\infty)$ fixed, we consider the parabolic initial boundary value problem (IBVP)

$$\begin{cases} \partial_t u - \Delta u = F(t,x) & \text{in } Q := (0,T) \times \Omega, \\ u(0,\cdot) = 0 & \text{in } \Omega, \\ u = 0 & \text{on } \Sigma := (0,T) \times \Gamma, \end{cases} \tag{1.1}$$

with source term $F \in L^2(Q)$. In this paper, we examine the inverse problem of determining F from a single Neumann boundary measurement of the solution u to (1.1) given by $\partial_\nu u$ with ν the outward unit normal vector of $\partial\Omega$.

Let us first notice that there is a natural obstruction to uniqueness in this problem. This can be seen by considering the solution u to (1.1) associated with $F = \partial_t \chi - \Delta\chi$, where χ is arbitrary in $\mathcal{C}_0^\infty(Q)$. Evidently we have $u = \chi$ by the uniqueness of the solution to (1.1). Moreover, if χ is not uniformly zero in Q then the same is true for F (otherwise u would be zero everywhere by virtue of the uniqueness of the solution to (1.1)), despite of the fact that

$$\partial_\nu u(t,x) = \partial_\nu \chi(t,x) = 0, \ (t,x) \in \Sigma.$$

Therefore, there exist infinitely many source terms F boundary observation remains unchanged whereas the source term is changed into F from zero everywhere in Q. This establishes that knowledge of $\partial_\nu u$ on Σ does not uniquely determines F. To overcome this problem, different lines

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of research can be pursued. One of them is to extend the set of data available in such a way that F is uniquely determined by these observations. Another direction is the one of assuming that the source term F is *a priori* known to have the structure

$$F(t,x) = \sigma(t)\beta(x), \quad (t,x) \in Q, \tag{1.2}$$

where $t \mapsto \sigma(t)$ is a known function, and then proving that knowledge of $\partial_\nu u$ uniquely determines β. In this paper we investigate the second direction. Namely we examine the stability issue in the identification of the time-independent part β of the source, from partial observation on Σ of the flux $\partial_\nu u$ induced by the solution u to (1.1).

Source terms of the form (1.2) are commonly associated with the reaction term in linear reaction diffusion equations. These equations arise naturally in various fields of application investigating systems made of several interacting components, such as population dynamics [21], fluid dynamics [3] or heat conduction [4]. More precisely when $\sigma(t) := e^{-\mu t}$, where μ is a positive constant, the system (1.1)-(1.2) describes the diffusion of decay heat (that is the heat released as a result of radioactive decay) in transmission lines or cooling pipes with significantly large length-to-diameter ratio. In this particular case, (1.2) models a heat source produced by the decay of a radioactive isotope and β is the spatial density of the isotope. From a practical viewpoint, the rate of decay μ of the isotope inducing the decay heat diffusion process is known and therefore the same is true for the function σ, while the density function β is generally unknown. This motivates for a closer look into the inverse problem under investigation in this article.

1.2 Existing papers: a short review

Inverse source problems have been extensively studied over the previous decades. We refer to [17] for a more general overview of this topic than the one presented in this section, where we solely focus on parabolic inverse source problems consisting in determining a source term by boundary measurements of the solution to a parabolic equation. The uniqueness issue for this problem was investigated in [7] and conditional stability was derived in [10, 23, 24]. In [18], inspired by the Bukhgeim-Klibanov approach introduced in [6], Imanuvilov and Yamamoto proved Lipschitz stability of the source with respect to one Neumann boundary measurement of the solution to a parabolic equation with non-degenerate initial data and partial Dirichlet data supported on arbitrary subregions of the boundary. In [11], Choulli and Yamamoto established a log-type stability estimate for the time-independent source term β appearing in (1.2), by a single Neumann observation of the solution on an arbitrary sub-boundary.

All the above mentioned results are stated in a bounded spatial domain. But, to the best of our knowledge, there is no result available in the mathematical literature dealing with the recovery of a non-compactly supported unknown source function appearing in a parabolic equation, by boundary measurements of the solution. This is the starting point of this paper in the sense that we aim for extending the stability result of [11], which is valid in bounded spatial domains only, to the framework of infinite cylindrical domains.

1.3 The forward problem

Prior to describing the main achievement of this paper in Section 1.4, we briefly investigate the well-posedness of the IBVP(1.1). Actually we start by examining the forward problem associated with the IBVP

$$\begin{cases} \partial_t v - \Delta v = f & \text{in } Q, \\ v(0,\cdot) = v_0 & \text{in } \Omega, \\ v = 0 & \text{on } \Sigma, \end{cases} \tag{1.3}$$

for suitable source term f and initial data v_0. More precisely we seek an existence, uniqueness and (improved) regularity result for the solution to the above system, as well as a suitable energy

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estimate. Such results are rather classical in the case of bounded spatial domains but it turns out that they are not so well-documented for unbounded domains such as Ω. Therefore, for the sake of completeness, we shall establish Theorem 1.1, presented below.

As a preliminary we introduce the following notations. With reference to [22, Section 4.2.1] we endow the space

$$\mathscr{H}^s(\Omega) := L^2(\mathbb{R}; H^s(\omega)) \cap H^s(\mathbb{R}; L^2(\omega)), \ s \in (0, +\infty),$$

with the norm $\|u\|_{\mathscr{H}^s(\Omega)}^2 := \|u\|_{L^2(\mathbb{R}; H^s(\omega))}^2 + \|u\|_{H^s(\mathbb{R}; L^2(\omega))}^2$ and we put

$$H^{r,s}(Q) := L^2\big(0, T; \mathscr{H}^r(\Omega)\big) \cap H^s(0, T; L^2(\Omega)), \ r, s \in [0, +\infty).$$

Here and hereinafter the symbol H^s stands for the usual Sobolev space of order s and $H_0^1(\Omega)$ is the closure of $\mathcal{C}_0^\infty(\Omega)$ in the $H^1(\Omega)$-topology. We recall for further use that

$$H_0^1(\Omega) = \{u \in H^1(\Omega): \ u_{|\partial\Omega} = 0\}$$

and we point out from [22, Proposition 2.3, Chapter 4] that the space $\mathscr{H}^k(\Omega)$ coincides with $H^k(\Omega)$, with equivalent norms, provided we have $k \in \mathbb{N} := \{1, 2, \ldots\}$.

Having said that, we may now state the following forward result associated with (1.3).

Theorem 1.1 *Let $v_0 \in H_0^1(\Omega)$ and $f \in L^2(0, T; H_0^1(\Omega))$. Then, there exists a unique solution $v \in H^{2,1}(Q) \cap \mathcal{C}([0,T]; H_0^1(\Omega))$ to the IBVP (1.3), such that*

$$\|v(t)\|_{H^1(\Omega)} \leq \|v_0\|_{H^1(\Omega)} + T^{1/2}\|f\|_{L^2(0,T;H^1(\Omega))}, \ t \in [0, T]. \tag{1.4}$$

As will be seen in the sequel, Theorem 1.1 is a crucial step in the derivation of the observability inequality presented in Section 4.1, which is a cornerstone in the analysis of the inverse problem under investigation. But, just as important is the following consequence of Theorem 1.1, which enables us to define properly the boundary data used for identifying the unknown function β in Theorem 1.2, below.

Corollary 1.1 *Let F be defined by (1.2), where $\sigma \in \mathcal{C}^1([0,T])$ and $\beta \in H_0^1(\Omega)$. Then the IBVP (1.3) admits a unique solution $u \in H^{2,1}(Q)$. Moreover we have $\partial_t u \in H^{2,1}(Q) \cap \mathcal{C}([0,T]; H_0^1(\Omega))$ and the following estimate holds:*

$$\|\partial_t u(t)\|_{H^1(\Omega)} \leq (1 + T)\|\sigma\|_{\mathcal{C}^1([0,T])}\|\beta\|_{H^1(\Omega)}, \ t \in [0, T]. \tag{1.5}$$

The proofs of Theorem 1.1 and Corollary 1.1 are presented in Section 2.

1.4 Main result

For $M \in (0, +\infty)$ fixed, we introduce the set of admissible unknown source functions as

$$B(M) := \left\{\varphi \in H_0^1(\Omega); \|\varphi\|_{H^1(\Omega)} \leq M\right\} \tag{1.6}$$

and we state the main result of this article as follows.

Theorem 1.2 *Put $\gamma := \gamma' \times \mathbb{R}$, where γ' is an arbitrary closed subset of the boundary $\partial\omega$ with non empty interior, and let $\sigma \in \mathcal{C}^1([0,T])$ satisfy $\sigma(0) \neq 0$. For $M \in (0, +\infty)$, pick $\beta \in B(M)$ and let u be the $H^{2,1}(Q)$-solution to the IBVP (1.1) associated with*

$$F(t, x) = \sigma(t)\beta(x), \ (t, x) \in Q,$$

which is given by Corollary 1.1. Then there exists a constant $C > 0$, depending only on ω, σ, T, M and γ', such that the estimate

$$\|\beta\|_{L^2(\Omega)} \leq C\Phi\left(\|\partial_\nu u\|_{H^1(0,T;L^2(\gamma))}\right),\tag{1.7}$$

holds with

$$\Phi(r) := \begin{cases} r^{1/2} + |\ln r|^{-1/2} & \text{if } r \in (0,+\infty) \\ 0 & \text{if } r = 0. \end{cases}\tag{1.8}$$

Notice that we have $u \in H^1(0,T;H^2(\Omega))$ from Corollary 1.1, which guarantees that the trace $\partial_\nu u$ appearing in the right hand side of the stability estimate (1.8) is well-defined in $H^1(0,T;L^2(\gamma))$.

To the best of our knowledge, Theorem 1.2 is the first stability result in the identification of the non-compactly supported source term β, appearing in a parabolic equation, by a single partial boundary observation of the solution. A similar statement was actually derived in [11, Theorem 2.2] (see also [9, Theorem 3.4]) when the domain Ω is bounded, so Theorem 1.2 extends this result to the case of infinite cylindrical domains.

Notice that the statement of Theorem 1.2 is valid in absence of any assumption on the behavior of the source term β outside a compact subset of the infinite cylindrical domain $\Omega = \omega \times \mathbb{R}$. Another remarkable feature of the result of Theorem 1.2 is that the logarithmic dependency of the space-varying source term, with respect to the boundary data, manifested in [11, Theorem 2.2] for a bounded domain, is preserved by the stability estimate (1.7). Otherwise stated, the stability of the reconstruction of β by a single boundary observation of the solution, is not affected by the infinite extension of the support of the unknown coefficient. This phenomenon is in sharp contrast with the one observed for the determination of the electric potential appearing in the Schrödinger equation, by a finite number of Neuman data, where Lipschitz stability (see [1, Theorem 1] and [2, Theorem 1]) degenerates to Hölder (see [20, Theorem 1.4]), as the support of the unknown potential becomes infinite.

The proof of Theorem 1.2 is by means of a Carleman inequality specifically designed for the heat operator in the unbounded cylindrical domain Ω. The derivation of this estimate is inspired by the approach used in this particular framework by [5, 19, 20] for the Schrödinger equation.

1.5 Outline

The paper is organized as follows. In Section 2, we establish Theorem 1.1 and Corollary 1.1. In Section 3, we derive a Carleman estimate for the heat operator in Ω, which is the main tool for the proof of the observability inequality presented in Section 4.1. Finally, Section 4 contains the proof of Theorem 1.2, which is by means of the above mentioned observability inequality.

2 Analysis of the forward problem

2.1 Proof of Theorem 1.1

Let A be the Dirichlet Laplacian in $L^2(\Omega)$, i.e. the self-adjoint operator generated in $L^2(\Omega)$ by the closed quadratic form

$$a(\varphi) := \int_\Omega |\nabla\varphi|^2 \; dx, \; \varphi \in D(a) := H_0^1(\Omega).$$

Evidently A acts as $-\Delta$ on its domain $D(A) := \{\varphi \in H_0^1(\Omega), \; \Delta\varphi \in L^2(\Omega)\}$ so we may rewrite the IBVP (1.3) into the following Cauchy problem

$$\begin{cases} v' + Av = & f \text{ in } (0,T), \\ v(0) = v_0. \end{cases}\tag{2.1}$$

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Further, since ω is bounded, then there exists a positive constant $c(\omega)$, depending only on ω, such that the Poincaré inequality holds:

$$a(\varphi) \geq c(\omega)\|\varphi\|_{L^2(\Omega)}^2, \ \varphi \in H_0^1(\Omega).$$

As a consequence we have $A \geq c(\omega)$ in the operator sense so $A + p$ is thus boundedly invertible in $L^2(\Omega)$ for all $p \in \mathbb{C} \setminus (0, +\infty)$, with

$$\|(A + p)^{-1}\|_{\mathcal{B}(L^2(\Omega))} \leq \frac{\sqrt{2}\max(1, c(\omega)^{-1})}{1 + |p|}, \ p \in \mathbb{C}, \ \mathrm{Re} \ p \geq 0.$$

Moreover, as $v_0 \in H_0^1(\Omega) = D(a) = D(A^{1/2})$ and $f \in L^2(Q)$, then we derive from [22, Section 4, Theorem 3.2] that (2.1) admits a unique solution

$$v \in L^2(0, T; D(A)) \cap H^1(0, T; L^2(\Omega)).$$

From this and the identity $D(A) = H^2(\Omega) \cap H_0^1(\Omega)$, arising from [12, Lemma 2.2], it then follows that $v \in H^{2,1}(Q)$.

The last step of the proof is to show that $v \in \mathcal{C}([0, T]; H_0^1(\Omega))$ satisfies (1.4). Bearing in mind that A is the infinitesimal generator of a contraction semi-group of class $\mathcal{C}^0$ in $L^2(\Omega)$ (see e.g. [13, Section XVII.A.3, Theorem 2]), this can be done with the aid of Duhamel's formula, giving

$$v(t) = e^{-tA}v_0 + \int_0^t e^{-(t-s)A}f(s) \ ds, \ t \in [0, T]. \tag{2.2}$$

Indeed, since $v_0 \in D(A^{1/2})$ and e^{-tA} commutes with $A^{1/2}$ for all $t \in [0, T]$, we have $e^{-tA}v_0 \in D(A^{1/2})$ and $A^{1/2}e^{-tA}v_0 = e^{-tA}A^{1/2}v_0$, which entails

$$t \mapsto e^{-tA}v_0 \in \mathcal{C}([0, T]; D(A^{1/2})) = \mathcal{C}([0, T]; H_0^1(\Omega)). \tag{2.3}$$

Furthermore, for all $t \in [0, T]$ we infer from the basic identity

$$\left\|e^{-tA}v_0\right\|_{H^1(\Omega)}^2 = \left\|e^{-tA}v_0\right\|_{L^2(\Omega)}^2 + \left\|A^{1/2}e^{-tA}v_0\right\|_{L^2(\Omega)}^2,$$

that

$$\begin{aligned}
\left\|e^{-tA}v_0\right\|_{H^1(\Omega)}^2 &= \left\|e^{-tA}v_0\right\|_{L^2(\Omega)}^2 + \left\|e^{-tA}A^{1/2}v_0\right\|_{L^2(\Omega)}^2 \\
&\leq \|v_0\|_{L^2(\Omega)}^2 + \left\|A^{1/2}v_0\right\|_{L^2(\Omega)}^2 \\
&\leq \|v_0\|_{H^1(\Omega)}^2.
\end{aligned} \tag{2.4}$$

Here we used the fact that the operator e^{-tA} is linear bounded in $L^2(\Omega)$ for all $t \in [0, T]$, with $\left\|e^{-tA}\right\|_{\mathcal{B}(L^2(\Omega))} \leq e^{-tc(\omega)} \leq 1$.

Similarly, since $f(s) \in D(A^{1/2})$ for a.e. $s \in (0, T)$, we get

$$t \mapsto \int_0^t e^{-(t-s)A}f(s) \ ds \in \mathcal{C}([0, T]; H_0^1(\Omega)), \tag{2.5}$$

by arguing as before. Next, taking into account that

$$\begin{aligned}
\left\|\int_0^t e^{-(t-s)A}f(s) \ ds\right\|_{H^1(\Omega)}^2 &= \left\|\int_0^t e^{-(t-s)A}f(s) \ ds\right\|_{L^2(\Omega)}^2 + \left\|A^{1/2}\int_0^t e^{-(t-s)A}f(s) \ ds\right\|_{L^2(\Omega)}^2 \\
&= \left\|\int_0^t e^{-(t-s)A}f(s) \ ds\right\|_{L^2(\Omega)}^2 + \left\|\int_0^t e^{-(t-s)A}A^{1/2}f(s) \ ds\right\|_{L^2(\Omega)}^2,
\end{aligned}$$

for every $t \in [0, T]$, we obtain

$$
\begin{aligned}
\left\| \int_0^t e^{-(t-s)A} f(s) \, ds \right\|_{H^1(\Omega)}^2
&\leq T \int_0^t \left(\left\| e^{-(t-s)A} f(s) \right\|_{L^2(\Omega)}^2 + \left\| e^{-(t-s)A} A^{1/2} f(s) \right\|_{L^2(\Omega)}^2 \right) \, ds \\
&\leq T \int_0^t \left(\| f(s) \|_{L^2(\Omega)}^2 + \left\| A^{1/2} f(s) \right\|_{L^2(\Omega)}^2 \right) \, ds \\
&\leq T \| f \|_{L^2(0,T;H^1(\Omega))}^2.
\end{aligned}
\tag{2.6}
$$

Finally, putting (2.2), (2.3) and (2.5) together, we find that $v \in \mathcal{C}([0,T]; H_0^1(\Omega))$, and (1.4) follows readily from (2.2), (2.4) and (2.6).

2.2 Proof of Corollary 1.1

Since $F \in L^2(0,T; H_0^1(\Omega))$ and the initial data of the IBVP (1.1) is zero everywhere, then there exists a unique solution $u \in H^{2,1}(Q)$ to (1.1), according to Theorem 1.1. Moreover, by differentiating (1.1) with respect to t, we obtain that $\partial_t u$ is solution to the system (1.3) associated with $f(t,x) = \sigma'(t)\beta(x) \in L^2(0,T; H_0^1(\Omega))$ and $v_0 := \sigma(0)\beta \in H_0^1(\Omega)$. Therefore we have $\partial_t u \in H^{2,1}(Q) \cap \mathcal{C}([0,T]; H_0^1(\Omega))$ from Theorem 1.1 and the estimate (1.4) yields

$$
\begin{aligned}
\| \partial_t u(t) \|_{H^1(\Omega)}
&\leq |\sigma(0)| \|\beta\|_{H^1(\Omega)} + T^{1/2} \|\sigma'(t)\beta(x)\|_{L^2(0,T;H^1(\Omega))} \\
&\leq \left(|\sigma(0)| + T \|\sigma'\|_{\mathcal{C}^0([0,T])} \right) \|\beta\|_{H^1(\Omega)},
\end{aligned}
$$

for all $t \in [0, T]$. This leads to (1.5).

3 A parabolic Carleman inequality in unbounded cylindrical domains

In this section we establish a Carleman estimate, stated in Theorem 3.1, for the heat operator

$$
Pu := (\partial_t - \Delta)u, \ u \in \mathcal{C}([0,T]; H_0^1(\Omega)) \cap H^{2,1}(Q).
\tag{3.1}
$$

3.1 A Carleman estimate for P

Let $\gamma := \gamma' \times \mathbb{R}$ be the same as in Theorem 1.2. With reference to [16, Lemma 1.1] (see also [8, Lemma 1.1]), we pick[1] a function $\psi_0 \in \mathcal{C}^4(\overline{\omega})$, such that

(c.i) $\psi_0(x') > 0$ for all $x' \in \overline{\omega}$;

(c.ii) $\exists \alpha_0 > 0$ such that $|\nabla' \psi_0(x')| \geq \alpha_0$ for all $x' \in \omega$;

(c.iii) $\partial_{\nu'} \psi_0(x') \leq 0$ for all $x' \in \partial\omega \backslash \gamma'$.

Here ∇' denotes the gradient with respect to $x' = (x_1, \ldots, x_{n-1}) \in \mathbb{R}^{n-1}$, i.e. $\nabla' f := (\partial_{x_1} f, \ldots, \partial_{x_{n-1}} f)$, and $\partial_{\nu'}$ is the normal derivative with respect to $\partial\omega$, that is $\partial_{\nu'} := \nu' \cdot \nabla'$ where ν' stands for the outward normal vector to $\partial\omega$.

Thus putting $\psi(x) = \psi(x', x_n) := \psi_0(x')$ for all $x = (x', x_n) \in \overline{\Omega}$, it is apparent that the function $\psi \in \mathcal{C}^4(\overline{\Omega}) \cap W^{4,\infty}(\Omega)$ satisfies the three following conditions:

(C.i) $\inf_{x \in \Omega} \psi(x) > 0$;

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[1]This is where the assumption that $\partial\Omega$ be $\mathcal{C}^4$ is needed.

(C.ii) $|\nabla\psi(x)| \geq \alpha_0 > 0$ for all $x \in \overline{\Omega}$;

(C.iii) $\partial_\nu\psi(x) \leq 0$ for all $x \in \Gamma\backslash\gamma$.

Here and hereinafter the notation ν stands for the outward unit normal vector to the boundary Γ and $\partial_\nu := \nu \cdot \nabla$. Evidently, $\nu = (\nu', 0)$, so we have $\partial_\nu\psi = \partial_{\nu'}\psi_0$, as the function ψ does not depend on the longitudinal variable x_n.

Next, for each $\rho \in (0, +\infty)$, we introduce the following weight function

$$\Phi_\rho(t,x) = \Phi_\rho(t,x') := g(t)\left(e^{\rho\psi(x')} - e^{2\rho\|\psi\|_{L^\infty(\Omega)}}\right) \text{ with } g(t) := \frac{1}{t(T-t)}, \ (t,x) \in Q, \quad (3.2)$$

and, for further use, we gather in the coming lemma several useful properties of Φ_ρ.

Lemma 3.1 *There exists a constant $\rho_0 \in (0, +\infty)$, depending only on ψ, such that the following statements hold uniformly in Q for all $\rho \in [\rho_0, +\infty)$:*

(a) $|\nabla\Phi_\rho| \geq \alpha := \frac{4\rho_0\alpha_0}{T^2} > 0$;

(b) $\nabla|\nabla\Phi_\rho|^2 \cdot \nabla\Phi_\rho \geq C_0\rho|\nabla\Phi_\rho|^3$;

(c) $\mathcal{H}(\Phi_\rho)\xi \cdot \xi + C_1\rho|\nabla\Phi_\rho||\xi|^2 \geq 0, \ \xi \in \mathbb{R}^{n-1} \times \mathbb{R}$;

(d) $|\partial_t|\nabla\Phi_\rho|^2| + |\Delta^2\Phi_\rho| + |\Delta|\nabla\Phi_\rho|| + \rho^{-1}(\Delta\Phi_\rho)^2 \leq C_2|\nabla\Phi_\rho|^3$;

(e) $|\partial_t^2\Phi_\rho| + |\nabla\Phi_\rho|^{-1}(\partial_t\Phi_\rho)^2 \leq C_3\lambda \, |\nabla\Phi_\rho|^3, \ \lambda \geq \lambda_0(\rho) := e^{4\rho\|\psi\|_{L^\infty(\Omega)}}$.

Here C_j, $j = 0, 1, 2, 3$, are positive constants depending only on T, ψ and α_0, and $\mathcal{H}(\Phi_\rho)$ denotes the Hessian matrix of Φ_ρ with respect to $x \in \Omega$.

The proof of Lemma 3.1 is postponed to Section 3.3.

Now, with reference to (3.2), we may state the following Carleman estimate for the operator P.

Theorem 3.1 *Let $u \in H^{2,1}(Q) \cap \mathcal{C}([0,T]; H_0^1(\Omega))$ be real valued. Then there exists $\rho_0 \in (0, +\infty)$ such that for every $\rho \in [\rho_0, +\infty)$ there is $\lambda_0 = \lambda_0(\rho) \in (0, +\infty)$, depending only α_0, ω, γ', T and ρ, such that the estimate*

$$\left\|e^{\lambda\Phi_\rho}(\lambda g)^{-1/2}\Delta u\right\|_{L^2(Q)} + \left\|e^{\lambda\Phi_\rho}(\lambda g)^{-1/2}\partial_t u\right\|_{L^2(Q)} + \left\|e^{\lambda\Phi_\rho}(\lambda g)^{1/2}|\nabla u|\right\|_{L^2(Q)}$$

$$+\left\|e^{\lambda\Phi_\rho}(\lambda g)^{\frac{3}{2}}u\right\|_{L^2(Q)} \leq C\left(\left\|e^{\lambda\Phi_\rho}Pu\right\|_{L^2(Q)} + \left\|e^{\lambda\Phi_\rho}(\lambda g)^{1/2}\partial_\nu u\right\|_{L^2((0,T)\times\gamma)}\right), \quad (3.3)$$

holds for all $\lambda \in [\lambda_0, +\infty)$ and some positive constant C that depends only on α_0, ω, γ', T, ρ and λ_0.

We point out that it is actually possible to adapt the Carleman inequality of Theorem 3.1 to more general differential operators of the form $\partial_t - \Delta + A(t,x) \cdot \nabla + q(t,x)$ with $A \in L^\infty(Q)^n$ and $q \in L^\infty(Q)$. Nevertheless, as will appear in Section 4 below, such an estimate is not needed by the analysis of the inverse source problem carried out in this article. Therefore, in order to avoid the inadequate expense of the size of this paper, we shall not go further into the matter.

3.2 Proof of Theorem 3.1

The proof of Theorem 3.1 is inspired by the ones of [8, Lemma 1.2], [14, Lemma 5.2] and [9, Theorem 3.4]. For the sake of notational simplicity we shall systematically omit the variables $t \in (0, T)$ and $x \in \Omega$ in front of the various functions appearing in this section.

Let ρ and λ be fixed in $(0, +\infty)$. We set $v := e^{\lambda \Phi_\rho} u$ in such a way that

$$\int_Q e^{2\lambda \Phi_\rho} (Pu)^2 dx dt = \int_Q (L_\lambda v)^2 dx dt \text{ with } L_\lambda := e^{\lambda \Phi_\rho} P e^{-\lambda \Phi_\rho}$$

and we split L_λ into the sum $L_\lambda = L_\lambda^+ + L_\lambda^-$, where

$$L_\lambda^+ := -\Delta - \lambda \partial_t \Phi_\rho - \lambda^2 |\nabla \Phi_\rho|^2 \text{ and } L_\lambda^- := \partial_t + 2\lambda \nabla \Phi_\rho \cdot \nabla + \lambda \Delta \Phi_\rho. \tag{3.4}$$

a) The first step of the proof is to show that the estimate

$$\int_Q (L_\lambda^+ v) L_\lambda^- v dx dt + \lambda \int_{(0,T) \times \gamma} |\partial_\nu \Phi_\rho| (\partial_\nu v)^2 d\sigma dt$$

$$\geq C_0 \lambda^3 \rho \int_Q |\nabla \Phi_\rho|^3 v^2 dx dt - 2 C_1 \lambda \rho \int_Q |\nabla \Phi_\rho| |\nabla v|^2 dx dt + R_0, \tag{3.5}$$

holds uniformly in $\rho \in [\rho_0, +\infty)$, with

$$R_0 := \lambda^2 \int_Q (\partial_t |\nabla \Phi_\rho|^2) v^2 dx dt + \frac{\lambda}{2} \int_Q \left(\partial_t^2 \Phi_\rho - \Delta^2 \Phi_\rho \right) v^2 dx dt, \tag{3.6}$$

where ρ_0 and the two constants C_0 and C_1 are the same as in Lemma 3.1. This can be done with the aid of (3.4), involving

$$
\begin{aligned}
(L_\lambda^+ v) L_\lambda^- v &= -(\Delta v) \partial_t v - 2\lambda (\Delta v) \nabla \Phi_\rho \cdot \nabla v - \lambda (\Delta v)(\Delta \Phi_\rho) v - \lambda (\partial_t \Phi_\rho) v \partial_t v \\
&\quad - 2\lambda^2 (\partial_t \Phi_\rho)(\nabla \Phi_\rho \cdot \nabla v) v - \lambda^2 (\partial_t \Phi_\rho)(\Delta \Phi_\rho) v^2 - \lambda^2 |\nabla \Phi_\rho|^2 v \partial_t v \\
&\quad - 2\lambda^3 |\nabla \Phi_\rho|^2 (\nabla \Phi_\rho \cdot \nabla v) v - \lambda^3 |\nabla \Phi_\rho|^2 (\Delta \Phi_\rho) v^2,
\end{aligned}
\tag{3.7}
$$

through standard computations, and by integrating separately each term appearing in the right hand side of (3.7) with respect to (t, x) over Q.

The first term is easily treated with an integration by parts. Taking into account that v vanishes on Σ and in $\{0, T\} \times \Omega$, we find that

$$-\int_Q (\Delta v) \partial_t v \, dx dt = \frac{1}{2} \int_Q \partial_t |\nabla v|^2 dx dt = 0. \tag{3.8}$$

To examine the second term we write

$$\nabla (\nabla \Phi_\rho \cdot \nabla v) = \mathcal{H}(\Phi_\rho) \nabla v + \mathcal{H}(v) \nabla \Phi_\rho,$$

where, in accordance with the notation introduced in Lemma 3.1, $\mathcal{H}(v)$ stands for the Hessian matrix of v with respect to $x \in \Omega$, and we integrate by parts. We get:

$$
\begin{aligned}
&-\int_Q (\Delta v) \nabla \Phi_\rho \cdot \nabla v \, dx dt \\
&= \int_Q \nabla v \cdot \nabla (\nabla \Phi_\rho \cdot \nabla v) \, dx dt - \int_\Sigma (\partial_\nu v) \nabla \Phi_\rho \cdot \nabla v \, d\sigma dt \\
&= \int_Q \mathcal{H}(\Phi_\rho) \nabla v \cdot \nabla v \, dx dt + \int_Q \mathcal{H}(v) \nabla \Phi_\rho \cdot \nabla v \, dx dt - \int_\Sigma (\partial_\nu \Phi_\rho)(\partial_\nu v)^2 \, d\sigma dt. \tag{3.9}
\end{aligned}
$$

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In the last integral we used the fact, arising from the identity $v_{|\Sigma} = 0$, that $\nabla v = (\partial_\nu v)\nu$ on Σ, or equivalently that the tangential derivative of v vanishes on Σ. Moreover, as we have

$$
\begin{aligned}
\int_Q \mathcal{H}(v)\nabla\Phi_\rho \cdot \nabla v \; dxdt &= \frac{1}{2}\int_Q \nabla\Phi_\rho \cdot \nabla(|\nabla v|^2) \; dxdt \\
&= -\frac{1}{2}\int_Q (\Delta\Phi_\rho)|\nabla v|^2 \; dxdt + \frac{1}{2}\int_\Sigma (\partial_\nu\Phi_\rho)|\nabla v|^2 \; d\sigma dt \\
&= -\frac{1}{2}\int_Q (\Delta\Phi_\rho)|\nabla v|^2 \; dxdt + \frac{1}{2}\int_\Sigma (\partial_\nu\Phi_\rho)(\partial_\nu v)^2 \; d\sigma dt,
\end{aligned}
$$

we infer from (3.9) that

$$
\begin{aligned}
-2\lambda\int_Q (\Delta v)\nabla\Phi_\rho \cdot \nabla v \; dxdt &= 2\lambda\int_Q \mathcal{H}(\Phi_\rho)|\nabla v|^2 \; dxdt - \lambda\int_Q (\Delta\Phi_\rho)|\nabla v|^2 \; dxdt \\
&\qquad -\lambda\int_\Sigma (\partial_\nu\Phi_\rho)(\partial_\nu v)^2 \; d\sigma dt.
\end{aligned} \tag{3.10}
$$

As for the third term entering the right hand side of (3.7), we obtain

$$
\begin{aligned}
-\lambda\int_Q (\Delta v)(\Delta\Phi_\rho)v \; dxdt &= \lambda\int_Q \nabla v \cdot \nabla\big((\Delta\Phi_\rho)v\big) \; dxdt \\
&= \frac{\lambda}{2}\int_Q \nabla(\Delta\Phi_\rho) \cdot \nabla v^2 \; dxdt + \lambda\int_Q (\Delta\Phi_\rho)|\nabla v|^2 \; dxdt \\
&= -\frac{\lambda}{2}\int_Q (\Delta^2\Phi_\rho)v^2 \; dxdt + \lambda\int_Q (\Delta\Phi_\rho)|\nabla v|^2 \; dxdt, \tag{3.11}
\end{aligned}
$$

by integrating by parts. Next, the fourth term reads

$$
-\lambda\int_Q (\partial_t\Phi_\rho)v\partial_t v \; dxdt = -\frac{\lambda}{2}\int_Q (\partial_t\Phi_\rho)\partial_t v^2 \, dxdt = \frac{\lambda}{2}\int_Q (\partial_t^2\Phi_\rho)v^2 dxdt, \tag{3.12}
$$

while the fifth one can be brought into the form

$$
-2\lambda^2\int_Q (\partial_t\Phi_\rho)v\nabla\Phi_\rho \cdot \nabla v \, dxdt = -\lambda^2\int_Q (\partial_t\Phi_\rho)\nabla\Phi_\rho \cdot \nabla v^2 dxdt. \tag{3.13}
$$

Quite similarly, the sixth and seventh terms may be rewritten as, respectively,

$$
\begin{aligned}
-\lambda^2\int_Q (\Delta\Phi_\rho)(\partial_t\Phi_\rho)v^2 \; dxdt &= \lambda^2\int_Q \nabla\Phi_\rho \cdot \nabla\big((\partial_t\Phi_\rho)v^2\big) \; dxdt \tag{3.14} \\
&= \lambda^2\int_Q (\partial_t\Phi_\rho)\nabla\Phi_\rho \cdot \nabla v^2 \; dxdt + \frac{\lambda^2}{2}\int_Q \big(\partial_t|\nabla\Phi_\rho|^2\big)v^2 \; dxdt,
\end{aligned}
$$

and

$$
-\lambda^2\int_Q |\nabla\Phi_\rho|^2 v\partial_t v \; dxdt = -\frac{\lambda^2}{2}\int_Q |\nabla\Phi_\rho|^2\partial_t v^2 \; dxdt = \frac{\lambda^2}{2}\int_Q \big(\partial_t|\nabla\Phi_\rho|^2\big)v^2 \; dxdt. \tag{3.15}
$$

Finally the two last terms in the right hand side of (3.7) are re-expressed as

$$
-2\lambda^3\int_Q |\nabla\Phi_\rho|^2(\nabla\Phi_\rho \cdot \nabla v)v \; dxdt = -\lambda^3\int_Q |\nabla\Phi_\rho|^2\nabla\Phi_\rho \cdot \nabla v^2 \; dxdt \tag{3.16}
$$

and

$$
\begin{aligned}
-\lambda^3\int_Q (\Delta\Phi_\rho)|\nabla\Phi_\rho|^2 v^2 \; dxdt &= \lambda^3\int_Q \nabla\Phi_\rho \cdot \nabla\big(|\nabla\Phi_\rho|^2 v^2\big) \; dxdt \tag{3.17} \\
&= \lambda^3\int_Q \big(\nabla|\nabla\Phi_\rho|^2 \cdot \nabla\Phi_\rho\big) v^2 \; dxdt + \lambda^3\int_Q |\nabla\Phi_\rho|^2\nabla\Phi_\rho \cdot \nabla v^2 \; dxdt.
\end{aligned}
$$

Thus, putting (3.7)–(3.17) together, we obtain that

$$\int_Q (L_\lambda^+ v) L_\lambda^- v \, dxdt + \lambda \int_\Sigma (\partial_\nu \Phi_\rho)(\partial_\nu v)^2 \, d\sigma dt$$

$$= \lambda^3 \int_Q (\nabla|\nabla\Phi_\rho|^2 \cdot \nabla\Phi_\rho) v^2 \, dxdt + 2\lambda \int_Q \mathcal{H}(\Phi_\rho)|\nabla v|^2 \, dxdt$$

$$+ \frac{\lambda}{2} \int_Q \left(\partial_t^2 \Phi_\rho - \Delta^2 \Phi_\rho\right) v^2 \, dxdt + \lambda^2 \int_Q \left(\partial_t |\nabla\Phi_\rho|^2\right) v^2 \, dxdt.$$

With reference to Points (b) and (c) in Lemma 3.1, this entails for all $\rho \in [\rho_0, +\infty)$ that

$$\int_Q (L_\lambda^+ v) L_\lambda^- v \, dxdt + \lambda \int_\Sigma (\partial_\nu \Phi_\rho)(\partial_\nu v)^2 \, d\sigma dt$$

$$\geq C_0 \lambda^3 \rho \int_Q |\nabla\Phi_\rho|^3 v^2 \, dxdt - 2C_1 \lambda \rho \int_Q |\nabla\Phi_\rho|^2 |\nabla v|^2 \, dxdt + R_0,$$

where R_0 is given by (3.6). Finally (3.5) follows immediately from (C.iii) and the above estimate.

b) Further, by remembering (3.4) we see that $\Delta v = -L_\lambda^+ v - \lambda^2 |\nabla\Phi_\rho|^2 v - \lambda(\partial_t \Phi_\rho) v$, whence

$$(\Delta v)^2 \leq 3 \left((L_\lambda^+ v)^2 + \lambda^4 |\nabla\Phi_\rho|^4 v^2 + \lambda^2 (\partial_t \Phi_\rho)^2 v^2\right). \tag{3.18}$$

Next, with reference to Point (a) in Lemma 3.1, we derive from (3.18) that

$$\left(\lambda|\nabla\Phi_\rho|\right)^{-1} (\Delta v)^2 \leq \frac{3}{\alpha\lambda} (L_\lambda^+ v)^2 + 3\lambda^3 |\nabla\Phi_\rho|^3 v^2 + 3\lambda|\nabla\Phi_\rho|^{-1} (\partial_t \Phi_\rho)^2 v^2, \tag{3.19}$$

for all $\rho \in [\rho_0, +\infty)$. This entails that

$$\int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1} (\Delta v)^2 \, dxdt \leq \frac{3}{\alpha\lambda} \int_Q (L_\lambda^+ v)^2 \, dxdt + 3 \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^3 v^2 \, dxdt + R_1, \tag{3.20}$$

with

$$R_1 := 3\lambda \int_Q |\nabla\Phi_\rho|^{-1} (\partial_t \Phi_\rho)^2 v^2 \, dxdt. \tag{3.21}$$

Further, taking into account that $v_{|\Sigma} = 0$, we get

$$\int_Q |\nabla\Phi_\rho| |\nabla v|^2 \, dxdt = - \int_Q |\nabla\Phi_\rho| v \Delta v \, dxdt + \frac{1}{2} \int_Q \left(\Delta|\nabla\Phi_\rho|\right) v^2 \, dxdt$$

upon integrating by parts. This and the estimate

$$\rho^{3/2} \lambda |\nabla\Phi_\rho| |v\Delta v| = \left(\left(\lambda|\nabla\Phi_\rho|\right)^{-1/2} |\Delta v|\right) \left(\rho^{3/2} \left(\lambda|\nabla\Phi_\rho|\right)^{\frac{3}{2}} |v|\right)$$

$$\leq \frac{1}{2} \left(\lambda|\nabla\Phi_\rho|\right)^{-1} (\Delta v)^2 + \frac{\rho^3}{2} \left(\lambda|\nabla\Phi_\rho|\right)^3 v^2$$

yield

$$\rho^{3/2} \lambda \int_Q |\nabla\Phi_\rho| |\nabla v|^2 \, dxdt \leq \frac{1}{2} \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1} (\Delta v)^2 \, dxdt + \frac{\rho^3}{2} \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^3 v^2 \, dxdt$$

$$+ \frac{\rho^{3/2}}{2} \lambda \int_Q \left(\Delta|\nabla\Phi_\rho|\right) v^2 \, dxdt.$$

From this and (3.20)-(3.21) it then follows that

$$\rho^{3/2} \lambda \int_Q |\nabla\Phi_\rho| |\nabla v|^2 \, dxdt + \frac{1}{2} \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1} (\Delta v)^2 \, dxdt$$

$$\leq \frac{3}{\alpha\lambda} \int_Q (L_\lambda^+ v)^2 \, dxdt + \left(3 + \frac{\rho^3}{2}\right) \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^3 v^2 \, dxdt + R_2,$$

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with

$$R_2 := R_1 + \frac{\rho^{3/2}}{2}\lambda \int_Q \left(\Delta|\nabla\Phi_\rho|\right)v^2 \; dxdt. \tag{3.22}$$

Therefore, upon substituting $\max(\rho_0, 6^{1/3})$ for ρ_0, we obtain for all $\rho \in [\rho_0, +\infty)$ that

$$\rho^{1/2}\lambda \int_Q |\nabla\Phi_\rho||\nabla v|^2 \; dxdt + \frac{1}{2}\int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1}(\Delta v)^2 \; dxdt$$

$$\leq \quad \frac{3}{\alpha\lambda}\int_Q (L_\lambda^+ v)^2 \; dxdt + \rho^3 \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^3 v^2 \; dxdt + R_2.$$

Putting this together with (3.5), we find

$$\frac{3}{\alpha\lambda}\int_Q (L_\lambda^+ v)^2 \; dxdt + \frac{2}{C_0}\int_Q (L_\lambda^+ v)L_\lambda^- v \; dxdt + \frac{2\lambda}{C_0}\int_{\gamma\times(0,T)}|\partial_\nu\Phi_\rho|(\partial_\nu v)^2 \; d\sigma dt$$

$$\geq \quad \left(\rho^{1/2} - \frac{4C_1}{C_0}\right)\rho\lambda \int_Q |\nabla\Phi_\rho||\nabla v|^2 \; dxdt + \rho \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^3 v^2 \; dxdt$$

$$+\frac{1}{2}\int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1}(\Delta v)^2 \; dxdt + R_3, \tag{3.23}$$

with

$$R_3 := \frac{2R_0}{C_0} - R_2. \tag{3.24}$$

Then, upon possibly enlarging ρ_0, in such a way that $\rho_0^{1/2} - 4(C_1/C_0)$ is lower bounded by a positive constant C_2, we infer from (3.23), that for all $\rho \in [\rho_0, +\infty)$,

$$\frac{3}{\alpha\lambda}\int_Q (L_\lambda^+ v)^2 \; dxdt + \frac{2}{C_0}\int_Q (L_\lambda^+ v)L_\lambda^- v \; dxdt + \frac{2\lambda}{C_0}\int_{\gamma\times(0,T)}|\partial_\nu\Phi_\rho|(\partial_\nu v)^2 \; d\sigma dt$$

$$\geq \quad C_2\lambda \int_Q |\nabla\Phi_\rho||\nabla v|^2 \; dxdt + \rho \int_Q \left(\lambda|\nabla\Phi_\rho|\right)^3 v^2 \; dxdt$$

$$+\frac{1}{2}\int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1}(\Delta v)^2 \; dxdt + R_3. \tag{3.25}$$

c) Further, since $\partial_t v = L_\lambda^- v - 2\lambda\nabla\Phi_\rho \cdot \nabla v - \lambda(\Delta\Phi_\rho)v$, by (3.4), we find upon arguing as in the derivation (3.19), that

$$\left(\lambda|\nabla\Phi_\rho|\right)^{-1}(\partial_t v)^2 \leq \frac{3}{\alpha\lambda}(L_\lambda^- v)^2 + 12\lambda|\nabla\Phi_\rho||\nabla v|^2 + \frac{3\lambda}{\alpha}(\Delta\Phi_\rho)^2 v^2,$$

which immediately entails

$$\int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1}(\partial_t v)^2 dxdt \leq \frac{3}{\alpha\lambda}\int_Q (L_\lambda^- v)^2 dxdt + \frac{12}{\alpha}\lambda \int_Q |\nabla\Phi_\rho||\nabla v|^2 dxdt + R_4, \tag{3.26}$$

with

$$R_4 := \frac{3\lambda}{\alpha}\int_Q (\Delta\Phi_\rho)^2 v^2 dxdt. \tag{3.27}$$

Putting (3.25) together with (3.26), we see that

$$\frac{3}{\alpha\lambda}\int_Q (L_\lambda^+ v)^2 dxdt + \frac{2}{C_0}\int_Q (L_\lambda^+ v)L_\lambda^- v \; dxdt + \frac{C_2}{8\alpha\lambda}\int_Q (L_\lambda^- v)^2 \; dxdt$$

$$+\frac{2\lambda}{C_0}\int_{\gamma\times(0,T)}|\partial_\nu\Phi_\rho|(\partial_\nu v)^2 \; d\sigma dt$$

$$\geq \quad \frac{C_2}{24}\int_Q \left(\lambda|\nabla\Phi_\rho|\right)^{-1}(\partial_t v)^2 \; dxdt + \frac{1}{2}\int_Q (\lambda|\nabla\Phi_\rho|)^{-1}(\Delta v)^2 \; dxdt + \frac{C_2\lambda}{2}\int_Q |\nabla\Phi_\rho||\nabla v|^2 \; dxdt$$

$$+\rho \int_Q (\lambda|\nabla\Phi_\rho|)^3 v^2 \; dxdt + R_5,$$

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where we have set

$$R_5 := R_3 - \frac{C_2}{24} R_4. \tag{3.28}$$

Therefore, bearing in mind that $L_\lambda = L_\lambda^+ + L_\lambda^-$, we get that

$$\frac{1}{C_0} \left(\int_Q (L_\lambda v)^2 \, dxdt + 2\lambda \int_{\gamma \times (0,T)} |\partial_\nu \Phi_\rho| (\partial_\nu v)^2 d\sigma dt \right)$$

$$\geq \frac{C_2}{24} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\partial_t v)^2 \, dxdt + \frac{1}{2} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\Delta v)^2 \, dxdt$$

$$+ \frac{C_2 \lambda}{2} \int_Q |\nabla \Phi_\rho| |\nabla v|^2 \, dxdt + \rho \int_Q (\lambda |\nabla \Phi_\rho|)^3 v^2 \, dxdt + R_5, \tag{3.29}$$

provided $\lambda \in [C_0(3 + C_2)\alpha^{-1}, +\infty)$.

d) Without restricting the generality of the reasoning, we may assume in the sequel (upon possibly substituting $C_0(3 + C_2)\alpha^{-1}$ for $\lambda_0(\rho)$) that $\lambda_0(\rho) \in [C_0(3 + C_2)\alpha^{-1}, +\infty)$. This way, putting Points (d) and (e) in Lemma 3.1 together with (3.6), (3.21), (3.22), (3.24) and (3.27) -(3.28), we find for any $\rho \in [\rho_0, +\infty)$ and $\lambda \in [\lambda_0(\rho), +\infty)$ that $|R_5|$ is majorized by $\rho \lambda^2 \int_Q |\nabla \Phi_\rho|^3 v^2 \, dxdt$, up to some positive multiplicative constant that is independent of ρ and λ. Therefore we obtain upon possibly enlarging ρ_0 that

$$|R_5| \leq \frac{\rho}{2} \int_Q (\lambda |\nabla \Phi_\rho|)^3 v^2 \, dxdt, \ \rho \in [\rho_0, +\infty), \ \lambda \in [\lambda_0(\rho), +\infty).$$

This and (3.29) then yield

$$\frac{1}{C_0} \left(\int_Q (L_\lambda v)^2 \, dxdt + 2\lambda \int_{\gamma \times (0,T)} |\partial_\nu \Phi_\rho| (\partial_\nu v)^2 d\sigma dt \right)$$

$$\geq \frac{C_2}{24} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\partial_t v)^2 \, dxdt + \frac{1}{2} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\Delta v)^2 \, dxdt$$

$$+ \frac{C_2 \lambda}{2} \int_Q |\nabla \Phi_\rho| |\nabla v|^2 \, dxdt + \frac{\rho}{2} \int_Q (\lambda |\nabla \Phi_\rho|)^3 v^2 \, dxdt, \tag{3.30}$$

provided $\rho \in [\rho_0, +\infty)$ and $\lambda \in [\lambda_0(\rho), +\infty)$. Next, since $v = e^{\lambda \Phi_\rho} u$, we have $e^{2\lambda \Phi_\rho} |\nabla u|^2 \leq 2 \left(|\nabla v|^2 + \lambda^2 |\nabla \Phi_\rho|^2 v^2 \right)$ so it ensues from (3.30) and Point (a) in Lemma 3.1 that

$$\frac{1}{C_0} \left(\int_Q (L_\lambda v)^2 \, dxdt + 2\lambda \int_{\gamma \times (0,T)} |\partial_\nu \Phi_\rho| (\partial_\nu v)^2 d\sigma dt \right)$$

$$\geq \frac{C_2}{24} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\partial_t v)^2 \, dxdt + \frac{1}{2} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\Delta v)^2 \, dxdt$$

$$+ \frac{C_2 \lambda}{4} \int_Q e^{2\lambda \Phi_\rho} |\nabla \Phi_\rho| |\nabla u|^2 \, dxdt + \frac{\lambda^3}{2} (\rho - C_2 \alpha^{-1}) \int_Q |\nabla \Phi_\rho|^3 v^2 \, dxdt.$$

Thus we get upon possibly substituting $C_2 \alpha^{-1} + 1$ for ρ_0, that

$$\frac{1}{C_0} \left(\int_Q (L_\lambda v)^2 \, dxdt + 2\lambda \int_{\gamma \times (0,T)} |\partial_\nu \Phi_\rho| (\partial_\nu v)^2 d\sigma dt \right)$$

$$\geq \frac{C_2}{24} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\partial_t v)^2 \, dxdt + \frac{1}{2} \int_Q (\lambda |\nabla \Phi_\rho|)^{-1} (\Delta v)^2 \, dxdt$$

$$+ \frac{C_2 \lambda}{4} \int_Q e^{2\lambda \Phi_\rho} |\nabla \Phi_\rho| |\nabla u|^2 \, dxdt + \frac{\lambda^3}{2} \int_Q |\nabla \Phi_\rho|^3 v^2 \, dxdt, \tag{3.31}$$

for all $\rho \in [\rho_0, +\infty)$ and $\lambda \in [\lambda_0(\rho), +\infty)$. Further, due to (3.2) and (C.ii), the estimates $|\partial_\nu \Phi_\rho| \leq C_4 g$ and $|\nabla \Phi_\rho|^i \geq C_5 g^i$ for $i \in \{-1, 1, 3\}$, hold in Q with two constants C_4 and C_5 depending only on ρ, ψ and α_0. Therefore, for all $\rho \in [\rho_0, +\infty)$ and $\lambda \in [\lambda_0(\rho), +\infty)$, (3.31) yields existence of a positive constant C_6 that depends only on ρ, T, ψ and α_0, such that

$$\int_Q (L_\lambda v)^2 \, dx dt + \int_{\gamma \times (0,T)} (\lambda g)(\partial_\nu v)^2 d\sigma dt$$

$$\geq \quad C_6 \left(\int_Q (\lambda g)^{-1}(\partial_t v)^2 \, dx dt + \int_Q (\lambda g)^{-1}(\Delta v)^2 \, dx dt \right.$$

$$\left. + \int_Q e^{2\lambda \Phi_\rho}(\lambda g)|\nabla u|^2 \, dx dt + \int_Q (\lambda g)^3 v^2 \, dx dt \right).$$

Finally (3.3) follows immediately from this upon remembering that $v = e^{\lambda \Phi_\rho} u$, $v_{|\Sigma} = 0$ and $(L_\lambda v)^2 = e^{2\lambda \Phi_\rho}(Pu)^2$.

3.3 Proof of Lemma 3.1

As in Section 3.2, we systematically omit in this proof the variables $t \in (0, T)$ and $x \in \Omega$ in front of the functions g, ψ or Φ_ρ.

a) We have
$$\nabla \Phi_\rho = \rho g e^{\rho \psi} \nabla \psi, \tag{3.32}$$
from the very definition (3.2) of Φ_ρ. Thus, using that $g(t) \geq 4T^{-2}$ for all $t \in (0, T)$, we deduce the estimate (a) directly from (3.32) and (C.ii).

b) With reference to (3.2) and (3.32), we see that

$$\nabla|\nabla \Phi_\rho| = \rho g \nabla \left(e^{\rho \psi}|\nabla \psi| \right) = \rho g \rho e^{\rho \psi} \left(|\nabla \psi|\nabla \psi + \nabla|\nabla \psi| \right) = \rho|\nabla \psi|\nabla \Phi_\rho + |\nabla \Phi_\rho| \frac{\nabla|\nabla \psi|}{|\nabla \psi|}$$

and hence

$$\nabla|\nabla \Phi_\rho|^2 \cdot \nabla \Phi_\rho \quad = \quad 2|\nabla \Phi_\rho|\nabla|\nabla \Phi_\rho| \cdot \nabla \Phi_\rho$$

$$= \quad 2 \left(\rho|\nabla \Phi_\rho|^3|\nabla \psi| + |\nabla \Phi_\rho|^2 \frac{\nabla|\nabla \psi| \cdot \nabla \Phi_\rho}{|\nabla \psi|} \right). \tag{3.33}$$

Next we have $\frac{|\nabla|\nabla \psi| \cdot \nabla \Phi_\rho|}{|\nabla \psi|} \leq C\alpha_0^{-1}|\nabla \Phi_\rho|$ by (C.ii), where $C = C(\psi)$ is a positive constant depending only on ψ, according to (C.ii). Therefore (3.33) yields

$$\nabla|\nabla \Phi_\rho|^2 \cdot \nabla \Phi_\rho \geq 2\rho\alpha_0 \left(1 - \frac{C}{\rho\alpha_0^2} \right) |\nabla \Phi_\rho|^3$$

and the estimate (b) follows readily from this upon taking $\rho_0 \in [2\alpha_0^2, +\infty)$.

c) For all natural numbers i and j in $\{1, 2, \ldots, n\}$, we get

$$\partial_{x_i}\partial_{x_j} \Phi_\rho = \rho g e^{\rho \psi} \left(\partial_{x_i}\partial_{x_j}\psi + \rho(\partial_{x_i}\psi)(\partial_{x_j}\psi) \right) = \left(\partial_{x_i}\partial_{x_j}\psi + \rho(\partial_{x_i}\psi)(\partial_{x_j}\psi) \right) \frac{|\nabla \Phi_\rho|}{|\nabla \psi|}$$

directly from (3.2) and (3.32). Thus, in light of (C.ii), each $|\partial_{x_i}\partial_{x_j} \Phi_\rho|$, for $i, j = 1, \ldots, n$, is upper bounded by $\rho|\nabla \Phi_\rho|$ up to some positive multiplicative constant that depends only on ψ and α_0. As a consequence there exists $C = C(\psi, \alpha_0) \in (0, +\infty)$ such that

$$\left| \mathcal{H}(\Phi_\rho)\xi \cdot \xi \right| \leq C\rho|\nabla \Phi_\rho||\xi|^2, \ \xi \in \mathbb{R}^{n-1} \times \mathbb{R}.$$

This immediately leads to (c).

d) In light of (3.32) we have

$$\rho g e^{\rho\psi}|\nabla\psi| = |\nabla\Phi_\rho|, \tag{3.34}$$

so it follows from (C.i) and (C.ii) that

$$g \leq \frac{|\nabla\Phi_\rho|}{\alpha_0}, \ \rho \in [1,+\infty), \tag{3.35}$$

and from the estimate $g \geq 4/T^2$ that

$$\rho e^{\rho\psi} \leq \frac{T^2}{4}|\nabla\Phi_\rho|. \tag{3.36}$$

Therefore, as $\partial_t|\nabla\Phi_\rho|^2 = 2(2t-T)\rho^2 g^3 e^{2\rho\psi}|\nabla\psi|^2$, we infer from (3.34)-(3.35) that

$$\left|\partial_t|\nabla\Phi_\rho|^2\right| \leq C(T,\alpha_0)|\nabla\Phi_\rho|^3. \tag{3.37}$$

Next we find

$$\Delta\Phi_\rho = \rho g e^{\rho\psi}\left(\Delta\psi + \rho|\nabla\psi|^2\right) \tag{3.38}$$

by direct calculation, and hence

$$\rho^{-1}(\Delta\Phi_\rho)^2 \leq C(\psi,\alpha_0)\rho|\nabla\Phi_\rho|^2 \leq C(T,\psi,\alpha_0)|\nabla\Phi_\rho|^3 \tag{3.39}$$

from (3.34) and (3.36). Quite similarly we have

$$\Delta|\nabla\Phi_\rho| = \rho g e^{\rho\psi}\left(\rho^2|\nabla\psi|^3 + \rho(\Delta\psi)|\nabla\psi| + 2\rho\nabla\psi\cdot\nabla|\nabla\psi| + \Delta|\nabla\psi|\right)$$

by virtue of (3.34), so we get

$$|\Delta|\nabla\Phi_\rho|| \leq C(\psi)\rho^3 g e^{\rho\psi} \leq C(\psi,T)|\nabla\Phi_\rho|^3 \tag{3.40}$$

with the help of (3.34) and (3.36). Last, with reference to (3.38), we see that

$$\Delta^2\Phi_\rho = \rho g e^{\rho\psi}(\rho\nabla\psi + \nabla)\cdot\left(\rho\left(\Delta\psi + \rho|\nabla\psi|^2\right)\nabla\psi + \rho\nabla|\nabla\psi|^2 + \nabla\Delta\psi\right),$$

which combined with (C.i) yields

$$\left|\Delta^2\Phi_\rho\right| \leq C(\psi,\alpha_0)\rho^4 g e^{\rho\psi} \leq C(\psi,T,\alpha_0)(\rho e^{-\rho\psi})\rho^3 g e^{2\rho\psi} \leq C(\psi,T,\alpha_0)\rho^3 g e^{2\rho\psi}.$$

Thus we have

$$\left|\Delta^2\Phi_\rho\right| \leq C(\psi,T,\alpha_0)|\nabla\Phi_\rho|^3$$

and inequality (d) follows immediately from this, (3.37) and (3.39)-(3.40).

e) Using (3.2) we get through direct computations that

$$\partial_t\Phi_\rho = (2t-T)g\Phi_\rho \text{ and } \partial_t^2\Phi_\rho(t,x) = 2\left(1 + (2t-T)^2 g\right)g\Phi_\rho.$$

From this and the basic estimate $|\Phi_\rho| \leq g e^{2\rho\|\psi\|_{L^\infty(\Omega)}}$ we derive that

$$|\partial_t\Phi_\rho| \leq T g^2 e^{2\rho\|\psi\|_{L^\infty(\Omega)}} \text{ and } |\partial_t^2\Phi_\rho| \leq \frac{2(4+T^4)}{T^2}g^3 e^{2\rho\|\psi\|_{L^\infty(\Omega)}}. \tag{3.41}$$

Further, as $\nabla\Phi_\rho = \rho g e^{\rho\psi}\nabla\psi$, we have $|\nabla\Phi_\rho| \geq \rho g \alpha_0$ by (C.ii), so it follows readily from (3.41) that

$$\left|\partial_t^2\Phi_\rho\right| + |\nabla\Phi_\rho|^{-1}(\partial_t\Phi_\rho)^2 \leq C(T,\alpha_0)g^3 e^{4\rho\|\psi\|_{L^\infty(\Omega)}} \leq C(T,\alpha_0)|\nabla\Phi_\rho|^3 e^{4\rho\|\psi\|_{L^\infty(\Omega)}}, \ \rho \in [1,+\infty).$$

This entails the estimate (e).

4 Proof of Theorem 1.2

The proof of Theorem 1.2 is based on an observability inequality that is derived in the coming section with the aid of the Carleman estimate (3.3).

4.1 Observability inequality

The statement we are aiming for is as follows.

Proposition 4.1 *Let γ' and γ be the same as in Theorem 1.2. For $v_0 \in H_0^1(\Omega)$, let v be the $H^{2,1}(Q) \cap \mathcal{C}([0,T], H_0^1(\Omega))$-solution given by Theorem 1.1, to the IBVP (1.3) associated with $f = 0$. Then there exists a constant $C > 0$, depending only on α_0, ω, γ', and T, such that we have*

$$\|v(T, \cdot)\|_{H^1(\Omega)} \le C\|\partial_\nu v\|_{L^2((0,T)\times\gamma)}. \tag{4.1}$$

Proof. Let us pick a function $\eta \in \mathcal{C}^\infty([0,T]; [0,1])$ obeying $\eta(t) = 0$ if $t \in \left[0, \frac{T}{4}\right]$ and $\eta(t) = 1$ if $t \in \left[\frac{3T}{4}, T\right]$, in such a way that $w := \eta v$ is solution to the following system:

$$\begin{cases} \partial_t w - \Delta w = \eta' v & \text{in} \quad Q, \\ w(0, \cdot) = 0 & \text{in} \quad \Omega, \\ w = 0 & \text{on} \quad \Sigma. \end{cases} \tag{4.2}$$

Then we get $\|w(T, \cdot)\|_{H^1(\Omega)} \le \|\eta' v\|_{L^2(0,T;H^1(\Omega))}$ from (1.4) and consequently we have

$$\|v(T, \cdot)\|_{H^1(\Omega)} = \|w(T, \cdot)\|_{H^1(\Omega)} \le \|\eta\|_{W^{1,\infty}(0,T)} \|v\|_{H^1\left(\left(\frac{T}{4}, \frac{3T}{4}\right)\times\Omega\right)}, \tag{4.3}$$

upon remembering that $\eta(T) = 1$ and η' vanishes in $\left(0, \frac{T}{4}\right) \cup \left(\frac{3T}{4}, T\right)$.

The next step of the proof is to apply the Carleman estimate (3.3) to v. For $\rho = \rho_0$ and $\lambda = \lambda_0(\rho)$ we obtain that

$$\|e^{\lambda\Phi_\rho}(\lambda g)^{\frac{3}{2}} v\|_{L^2(Q)} + \|e^{\lambda\Phi_\rho}(\lambda g)^{1/2}|\nabla v|\|_{L^2(Q)} \le c_1\|e^{\lambda\Phi_\rho}(\lambda g)^{1/2}\partial_\nu v\|_{L^2((0,T)\times\gamma)}, \tag{4.4}$$

where c_1 is a positive constant depending only on α_0, ω, γ' and T.

Further, since $g(t) \ge \frac{4}{T^2}$ for all $t \in (0,T)$ and since $\Phi_\rho(t,x) \ge -\frac{16}{3T^2}e^{2\rho\|\psi\|_{L^\infty(\Omega)}}$ for every $(t,x) \in \left(\frac{T}{4}, \frac{3T}{4}\right) \times \Omega$ by virtue of (3.2), we see that

$$\left(\frac{4\lambda}{T^2}\right)^{1/2} e^{-\frac{16}{3T^2}\lambda e^{2\rho\|\psi\|_{L^\infty(\Omega)}}} \left(\left(\frac{4\lambda}{T^2}\right) \|v\|_{L^2\left(\left(\frac{T}{4}, \frac{3T}{4}\right)\times\Omega\right)} + \||\nabla v|\|_{L^2\left(\left(\frac{T}{4}, \frac{3T}{4}\right)\times\Omega\right)}\right)$$
$$\le \|e^{\lambda\Phi_\rho}(\lambda g)^{\frac{3}{2}} v\|_{L^2(Q)} + \|e^{\lambda\Phi_\rho}(\lambda g)^{1/2}|\nabla v|\|_{L^2(Q)}. \tag{4.5}$$

On the other hand, for all $(t,x) \in (0,T) \times \gamma$ we have $\Phi_\rho(t,x) \le -c_2 g(t)$, where $c_2 := e^{2\rho\|\psi\|_{L^\infty(\Omega)}} - e^{\rho\|\psi\|_{L^\infty(\Omega)}} \in (0, +\infty)$ according to (3.2). This entails

$$\|e^{\lambda\Phi_\rho}(\lambda g)^{1/2}\partial_\nu v\|_{L^2((0,T)\times\gamma)} \le c_3\|\partial_\nu v\|_{L^2((0,T)\times\gamma)},$$

with $c_3 := \sup_{r\in(0,+\infty)} r^{1/2}e^{-c_2 r} \in (0, +\infty)$.

From this and (4.4)-(4.5) it then follows that

$$\|v\|_{H^1\left(\Omega\times\left(\frac{T}{4}, \frac{3T}{4}\right)\right)} \le c_4\|\partial_\nu v\|_{L^2((0,T)\times\gamma)}, \tag{4.6}$$

where c_4 is a positive constant depending only on α_0, ω, γ' and T. Finally we obtain Proposition 4.1 by combining (4.3) with (4.6). $\qquad\square$

Armed with Proposition 4.1 we may now complete the proof of Theorem 1.2.

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4.2 Completion of the proof

Due to [11, Remark, pp. 367] and the hypothesis $\sigma(0) \neq 0$ we may assume in the sequel without loss of generality that $\sigma(t) = 1$ for all $t \in [0, T]$.

a) *Time differentiation of the solution.* For $\beta \in H_0^1(\Omega)$ we denote by u the $H^{2,1}(\Omega) \cap \mathcal{C}([0,T], H_0^1(\Omega))$-solution given by Theorem 1.1 to the IBVP

$$\begin{cases} \partial_t u - \Delta u = \beta & \text{in} \quad Q, \\ u(0, \cdot) = 0 & \text{in} \quad \Omega, \\ u = 0 & \text{on} \quad \Sigma, \end{cases}$$

where the abuse of notation β stands for the function $Q \ni (t, x) \mapsto \beta(x) \in L^2(0, T; H_0^1(\Omega))$. Then $v := \partial_t u$ is a solution to the system

$$\begin{cases} \partial_t v - \Delta v = 0 & \text{in} \quad Q, \\ v(0, \cdot) = \beta & \text{in} \quad \Omega, \\ v = 0 & \text{on} \quad \Sigma, \end{cases} \tag{4.7}$$

and since $\beta \in H_0^1(\Omega)$, we get that $v \in H^{2,1}(Q) \cap \mathcal{C}([0,T]; H_0^1(\Omega))$ by applying Theorem 1.1.

b) *Fiber and spectral decompositions.* We stick with the notations of Section 2.1 and still denote by A the Dirichlet Laplacian in $L^2(\Omega)$, with domain $D(A) = H_0^1(\Omega) \cap H^2(\Omega)$. Let $\mathcal{F}_{x_n}$ be the partial Fourier transform with respect to x_n, defined for all $\varphi \in L^1(Q)$, by

$$\mathcal{F}_{x_n} \varphi(t, x', k) := (2\pi)^{-1/2} \int_{\mathbb{R}} \varphi(t, x', x_n) e^{-ikx_n} dx_n, \ (t, x') \in (0, T) \times \omega, \ k \in \mathbb{R},$$

and then suitably extended into a unitary operator in $L^2(Q)$. Due to the translational invariance of the operator A in the infinite direction x_n, we have

$$\mathcal{F}_{x_n} A \mathcal{F}_{x_n}^{-1} = \int_{\mathbb{R}}^{\oplus} H(k) dk, \tag{4.8}$$

where $H(k) := A' + k^2$ and A' is the Dirichlet Laplacian in $L^2(\omega)$. Since the multiplier by k^2 is bounded in $L^2(\omega)$ then we have $D(H(k)) = D(A') = H_0^1(\omega) \cap H^2(\omega)$.

Further, as ω is bounded, we know that the resolvent of the operator A' is compact, and that the spectrum of A' is purely discrete. We denote by $\{\lambda_\ell, \ \ell \geq 1\}$ the sequence of (positive) eigenvalues of A', arranged in non-decreasing order and repeated according to their multiplicity. Next we introduce a Hilbert basis $\{\varphi_\ell, \ \ell \geq 1\}$ in $L^2(\omega)$, of eigenfunctions of A', i.e.

$$A' \varphi_\ell = \lambda_\ell \varphi_\ell, \ \ell \geq 1.$$

Then, putting $\hat{v}(\cdot, \cdot, k) := \mathcal{F}_{x_n} v(\cdot, \cdot, k)$ and $\hat{\beta}(\cdot, k) := \mathcal{F}_{x_n} \beta(\cdot, k)$ for all $k \in \mathbb{R}$, we find upon applying the transform $\mathcal{F}_{x_n}$ to both sides of (4.7), that

$$\begin{cases} \partial_t \hat{v}(\cdot, \cdot, k) + H(k) \hat{v}(\cdot, \cdot, k) = 0 & \text{in} \quad (0, T) \times \omega, \\ \hat{v}(0, \cdot, k) = \hat{\beta}(\cdot, k) & \text{in} \quad \omega, \\ \hat{v}(\cdot, \cdot, k) = 0 & \text{on} \quad (0, T) \times \partial\omega. \end{cases}$$

Therefore each function $(0, T) \ni t \mapsto v_{k,\ell}(t) := \langle \hat{v}(t, \cdot, k), \varphi_\ell \rangle_{L^2(\omega)}$, for $(k, \ell) \in \mathbb{R} \times \mathbb{N}^* := \{1, 2, \ldots\}$, is a solution to the differential equation $v'_{k,\ell} + (\lambda_\ell + k^2) v_{k,\ell} = 0$ in $(0, T)$, with initial data $v_{k,\ell}(0) = \beta_{k,\ell} := \langle \hat{\beta}(\cdot, k), \varphi_\ell \rangle_{L^2(\omega)}$. As a consequence we have

$$v_{k,\ell}(t) = \beta_{k,\ell} e^{-(\lambda_\ell + k^2)t}, \ t \in [0, T], \ (k, \ell) \in \mathbb{R} \times \mathbb{N}^*.$$

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We notice for further use from the above identity that

$$\beta_{k,\ell} = e^{(\lambda_\ell + k^2)T} v_{k,\ell}(T), \ (k,\ell) \in \mathbb{R} \times \mathbb{N}^*. \tag{4.9}$$

c) *Splitting energies.* Let us introduce the measure $\mu := \sum_{\ell \in \mathbb{N}^*} \delta_\ell$ on $\mathbb{R}$, where δ_ℓ denotes the delta Dirac measure at ℓ, in such a way that $\|\beta\|_{L^2(\Omega)}^2 = \int_{\mathbb{R}^2} |\beta_{k,\ell}|^2 d\mu(\ell) dk$ from the Plancherel formula. Thus it holds true for all fixed $\lambda \in (\lambda_1, +\infty)$ that

$$\|\beta\|_{L^2(\Omega)}^2 = \int_{\mathcal{E}_\lambda} |\beta_{k,\ell}|^2 d\mu(\ell) dk + \int_{\mathbb{R}^2 \setminus \mathcal{E}_\lambda} |\beta_{k,\ell}|^2 d\mu(\ell) dk,$$

where $\mathcal{E}_\lambda := \{(k,\ell) \in \mathbb{R} \times \mathbb{N}^*; \ \lambda_\ell + k^2 \leq \lambda\}$ is the set of energies lower or equal to λ. In light of (4.9) this entails that

$$
\begin{aligned}
\|\beta\|_{L^2(\Omega)}^2 &\leq \int_{\mathcal{E}_\lambda} e^{2(\lambda_\ell + k^2)T} |v_{k,\ell}(T)|^2 d\mu(\ell) dk + \frac{1}{\lambda} \int_{\mathbb{R}^2} (\lambda_\ell + k^2) |\beta_{k,\ell}|^2 d\mu(\ell) dk \\
&\leq e^{2\lambda T} \int_{\mathbb{R}^2} |v_{k,\ell}(T)|^2 d\mu(\ell) dk + \frac{1}{\lambda} \int_{\mathbb{R}^2} (\lambda_\ell + k^2) |\beta_{k,\ell}|^2 d\mu(\ell) dk \\
&\leq e^{2\lambda T} \|v(T, \cdot)\|_{L^2(\Omega)}^2 + \frac{1}{\lambda} \int_{\mathbb{R}^2} (\lambda_\ell + k^2) |\beta_{k,\ell}|^2 d\mu(\ell) dk. \tag{4.10}
\end{aligned}
$$

Further we have $\int_{\mathbb{R}^2} (\lambda_\ell + k^2) |\beta_{k,\ell}|^2 d\mu(\ell) dk = \int_{\mathbb{R}} \|H(k)^{1/2} \hat{\beta}(\cdot, k)\|_{L^2(\omega)}^2 dk = \|A^{1/2} \beta\|_{L^2(\Omega)}^2 = \|\nabla \beta\|_{L^2(\Omega)^n}^2$ in virtue of (4.8), and consequently

$$\int_{\mathbb{R}^2} (\lambda_\ell + k^2) |\beta_{k,\ell}|^2 d\mu(\ell) dk \leq \|\beta\|_{H^1(\Omega)}^2 \leq M^2. \tag{4.11}$$

Moreover we get by applying Proposition 4.1 to the solution v of the IBVP (4.7), that

$$\|v(T, \cdot)\|_{H^1(\Omega)} \leq C \|\partial_\nu v\|_{L^2((0,T) \times \gamma)} \leq C \|\partial_\nu u\|_{H^1(0,T;L^2(\gamma))}.$$

Putting this together with (4.10)-(4.11) we obtain

$$\|\beta\|_{L^2(\Omega)}^2 \leq \left(C e^{2\lambda T} \kappa^2 + \frac{M^2}{\lambda} \right), \tag{4.12}$$

where $\kappa := \|\partial_\nu u\|_{H^1(0,T;L^2(\gamma))} \in [0, +\infty)$.

Having established (4.12), we investigate each of the three cases $\kappa = 0$, $\kappa \in (0, e^{-2T\lambda_1})$ and $\kappa \in [e^{-2T\lambda_1}, +\infty)$, separately. We start with $\kappa \in (0, e^{-2T\lambda_1})$. In this case, taking $\lambda = -\frac{\ln \kappa}{2T}$ in (4.12) leads to

$$\|\beta\|_{L^2(\Omega)}^2 \leq C \left(\kappa + |\ln(\kappa)|^{-1} \right) \leq C \left(\kappa^{1/2} + |\ln(\kappa)|^{-1/2} \right)^2, \tag{4.13}$$

which is exactly the statement (1.7). Moreover we find $\beta = 0$ by sending κ to 0 in (4.13), which entails (1.7) with $\kappa = 0$. Finally, since it is apparent for all $\kappa \in [e^{-2T\lambda_1}, +\infty)$ that

$$\|\beta\|_{L^2(\Omega)} \leq M \leq M e^{T\lambda_1} \left(\kappa^{1/2} + |\ln(\kappa)|^{-1/2} \right),$$

then (1.7) holds for any $\kappa \in [0, +\infty)$, and the proof of Theorem 1.2 is complete.

Acknowledgements

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